

# Small C++

C vs. C++ code size on 8-bit AVR

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LUGS, Zurich, January 2014



# Overview

## Introduction

- ▶ **Hardware**
- ▶ Design
- ▶ C++

## Code



# Hardware Patterns

- ▶ 8bit Coprocessor
- ▶ Realtime Coprocessor
- ▶ Peripheral Coprocessor
- ▶ Hardware Watchdog



# 8bit Coprocessor

- ▶ Name: "8-bit Coprocessor"
- ▶ Problem: Some logic is hard to do in hardware
- ▶ Forces:
  - ▶ some things are hard in hardware
  - ▶ but don't fit into main CPU
  - ▶ 8-bit processors a cheap
    - ▶ as components and in manufacturing
- ▶ Solution:
  - ▶ Use separate 8-bit coprocessors



# Realtime Coprocessor

- ▶ Name: "Realtime Coprocessor"
- ▶ Problem:
  - ▶ Favoured OS clashes with realtime requirements
- ▶ Forces:
  - ▶ Some protocols or hardware have hard realtime requirements
  - ▶ Selected well-known widely-used OS cannot provide the required realtime guarantees
- ▶ Solution: Add a separate, dedicated realtime controller
- ▶ Consequences:
  - ▶ additional hardware costs
  - ▶ devide and conquer



# Peripheral Coprocessor

- ▶ Name: "Peripheral Coprocessor"
  - ▶ variation of "Realtime Coprocessor"
- ▶ Problem:
  - ▶ Special protocol with hard latency or throuput requirements
- ▶ Forces:
  - ▶ similar as for "Realtime Coprocessor"
  - ▶ implementation in main processor would be problematic
  - ▶ same protocol is used in different systems
  - ▶ doesn't exist as COTS
- ▶ Solution:
  - ▶ implement it in software on a separate processor



# Hardware Watchdog

- ▶ Name: "Intelligent External Watchdog"
- ▶ Problem: Watchdog timer devices are inflexible
- ▶ Forces:
  - ▶ external watchdog shall reset the main processor after some time of missing heartbeat
  - ▶ but boot time is longer
  - ▶ and not during firmware update
  - ▶ after specific number of unsuccessful attempts some alarm shall go off
- ▶ Solution:
  - ▶ use separate "8-bit Controller" with watchdog software



# AVR

AVR is a popular 8-bit microcontroller architecture by Atmel

- ▶ tinyAVR start at 512B flash and no RAM (but 32 registers)
- ▶ megaAVR start at 4K flash and 512B RAM

AVR is used on the Arduino boards



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# Flexible Design

”Design for Change”

Keep the design flexibel

- ▶ extendable:
  - ▶ It's easy to add new functionality
- ▶ adaptable:
  - ▶ It's easy to change existing functionality
- ▶ reusable:
  - ▶ Reuse of parts in other systems
  - ▶ Reuse parts from other systems



# Object Benefits

- ▶ Reliability
  - ▶ It runs, and runs, and runs ...
  - ▶ smaller units
  - ▶ cleaner code
  - ▶ more robust code
- ▶ Reusability
  - ▶ Special versions, different hardware and similar systems
  - ▶ classes as re-usable unit



# Reliability

- ▶ Smaller Units
  - ▶ Small is beautiful.
- ▶ Cleaner Code
  - ▶ Ease the code review.
- ▶ More Robust Code
  - ▶ Let the compiler do the work!



# Smaller Units

- ▶ Classes are protected units.
  - ▶ Nobody can change (or access) your data without your control.
  - ▶ Users of your class are constrained to the published interface.
- ▶ Classes have explicit interfaces.
  - ▶ You can change the implementation.
  - ▶ You can substitute a class by your own version.
- ▶ Classes are self-contained.
  - ▶ You can re-use them elsewhere.
  - ▶ Again: you can substitute them.
- ▶ Classes are plugged into frameworks.
  - ▶ Re-use complete architectures.



# Cleaner Code

- ▶ Small units
  - ▶ In smaller, self-contained units, mistakes are much easier to spot.
- ▶ Clear responsibilities
  - ▶ From the published interface, it's clear what you have to do – and what's an SEP.
- ▶ Clear delegation
  - ▶ If something is not your problem, it's clear who else is responsible for that.



# More Robust Code

- ▶ Automatic initialization
  - ▶ Nobody can forget to make a clean start – the compiler cares for you.
- ▶ Automatic cleanup
  - ▶ Never again forget to free your locks or your memory – again the compiler (together with useful library classes) cares for you.
- ▶ Protected separations
  - ▶ The compiler enforces your boundaries.



# Reusability

- ▶ Classes are easier to re-use than functions (not easy!)
  - ▶ Self containment (enforce this!)
  - ▶ Clear responsibilities
- ▶ Plug-in components into framework.



# Reusability

Reusability for embedded systems is often much easier (and more important) than for desktop systems

- ▶ Special versions
  - ▶ A customer wants some of the functionality a littlebit different.
- ▶ Different hardware
  - ▶ For embedded systems, porting is often the daily work:
    - ▶ different components to drive
    - ▶ new hardware line
    - ▶ new microcontrollers
- ▶ Similar systems
  - ▶ If you write the software for one microwave, chances are good that you have to write one for a different model.



# Embedded Design

- ▶ Constraints
  - ▶ Memory, performance, real-time
- ▶ Well known environment
  - ▶ You can plan in advance
- ▶ System programming
  - ▶ Low-level
  - ▶ Resource management
  - ▶ Multi-tasking
    - ▶ possibly multi-processing



# Embedded Objects

- ▶ Object-Oriented Programming often uses a lot of objects
  - ▶ short-lived
  - ▶ heap-based (at least partly)
  - ▶ dynamic memory allocation
- ▶ Dynamic memory allocation is often a problem in embedded systems
  - ▶ non-deterministic runtime
  - ▶ may fail



# Embedded Objects

- ▶ In embedded systems, OO must be used carefully
  - ▶ mechanisms depending on architectural level
  - ▶ special "libraries" for specific needs
  - ▶ always think about consequences
- ▶ Golden optimization rule ("Don't optimize now") only partially true
- ▶ Don't use OO for OO's sake
- ▶ Use dynamic memory allocation carefully



# Summary Benefits

- ▶ Though the OO (and C++) mechanisms sometimes cost you a bit, the benefits nearly always outweigh the costs:
  - ▶ You create your systems faster (through less debugging and more re-use).
  - ▶ You create more reliable systems (due to cleaner code).
  - ▶ Your systems are more flexible and therefore the time to market for variations is much shorter.



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# C++ History

C++ was designed from the beginning as a system programming language.

C++ was designed to solve a problem – a complex, low (system) level one.

Design goals:

- ▶ Tool to avoid programming mistakes as much as possible at compile time
- ▶ Tool to support design – not only implementation
- ▶ C performance
- ▶ High portability
- ▶ Low level
- ▶ Zero-overhead rule (“Don’t pay for what you don’t use.”)



# C++ Language Costs

- ▶ "TASATAFL"
- ▶ Generally, C++ is as fast as hand-coded assembler
  - ▶ but no rule without exception
- ▶ Abstraction mechanisms sometimes cost
  - ▶ program space
  - ▶ runtime data space
  - ▶ runtime performance
  - ▶ compile-time performance
- ▶ Non-abstraction solutions cost as well



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# AVR C++

- ▶ GCC has an AVR backend
  - ▶ No tinyAVR
  - ▶ RAM sizes starting from 128B (old devices)
- ▶ So GCC C++ also works
  - ▶ No exceptions
  - ▶ No placement new
  - ▶ No virtual destructors
  - ▶ No Standard C++ library
- ▶ AVR Libc library (<http://www.nongnu.org/avr-libc/>)
  - ▶ Provides fairly complete C library
  - ▶ Even `<stdio.h>` and `malloc()`
- ▶ Arduino provides a C++ library that's not used here.



# Code

- ▶ “Hello, World!” embedded:
  - ▶ blinking LEDs

